

**AMENDMENTS TO THE SPECIFICATION**

*Page 16, please amend the third and fourth full paragraphs to read as follows:*

An example of a tool unit WE is shown in Figure 4 together with a roller rail 4. In Figure 4 the reference number 4 indicates the roller rail, which is open underneath, whereby the holding device 3 formed from two rollers 12-1, 12-2 with an appropriate fixing device is suspended in this roller rail 4. A vertical guide is provided by the groove N and the stud S. The power supply is provide by two connectors 11, which are integrated into the roller rail 4. As shown in Figure 4, the holding device includes a current collecting slider SAS, which is in contact with the ~~busbars-conductors~~ 11.

The roller rail 4 can also include a data line 10 and a distance measuring ~~system-line~~ 9 for position determination ~~travelling~~ traveling box or trolley 31 also includes receiving devices for measuring the resistance of the position determining ~~bus-line~~ 9, for example, and a data receiving device for receiving and supplying data signals to the data line 10.

*Page 17, please amend the second full paragraph to read as follows:*

Other embodiments of the ~~busbar-4~~ roller rail, for example with a U-shaped profile which is open at the top, are also possible. It is also possible to carry out position determination via a rotation sensor in the individual rollers 12-1, 12-2, provided that no slippage of the rollers occurs lengthwise along the roller rail. AS is shown with the embodiment in Figure 4, through the arrangement of the integral ~~busbar-conductor~~ 11, the integral data line 10 and the integral distance measuring line 9, the machining tool WZ can be controlled with suitable parameters, power can be supplied without a trailing cable and in particular the assembly system can easily

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be rephrased and extended. This assembly system with no trailing cable installation is therefore described as a railnet assembly